PHOT 301: Quantum Photonics LECTURE 12B

Michaël Barbier, Fall semester (2024-2025)

INTRODUCTION TO DIFFERENT APPROXIMATIONS

APPROXIMATIONS

	Method	Approximates?
1	Transfer matrix method	piece-wise constant $V(x)$
2	Finite basis method	limited ψ_n , E_n : Matrix-formalism
3	Finite difference method	discretizes wave function
4	Perturbation theory (stat.)	small perturbation known solutions
5	Time-dependent perturbation	small perturbation known solutions
6	Tight-binding approx.	electrons strongly bound (covalent)
7	Variational method	finding energy minima

Usage of simple examples to compare over approximations

- Infinite square well with E-field (David Miller's book)
- Harmonic oscilator
- Transmission: Smoothed finite barrier

TRANSFER MATRIX METHOD IN 1D

- For 1D potential energy functions V(x) (here assume 1D systems)
- Approximation of potential energy V(x) by piece-wise constant V_i
- Transmission or bound states



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- Approximation of potential energy V(x) by piece-wise constant V_i
- Schrodinger equation for constant V(x) = V

$$rac{d^2\psi(x)}{dx^2}=-rac{2m}{\hbar^2}(E-V)\psi(x)$$

- Solution depends on value of E-V:
- If energy is larger than the potential energy E > V, then we have propagating waves

$$\psi(x)=Ae^{ikx}+Be^{-ikx}\qquad k^2=rac{2m}{\hbar^2}(E-V)$$

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$$rac{d^2\psi(x)}{dx^2}=-rac{2m}{\hbar^2}(E-V)\psi(x)$$

- Solution depends on value of E-V:
- If energy is less than the potential E < V, then we have evanescent waves:

$$\psi(x) = Ae^{-\kappa x} + Be^{\kappa x}$$
 $\kappa^2 = \frac{2m}{\hbar^2}(V - E)$

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- Approximation of potential energy V(x) by piece-wise constant V_i
- Schrodinger equation for constant V(x) = V

$$rac{d^2\psi(x)}{dx^2}=-rac{2m}{\hbar^2}(E-V)\psi(x)$$

- Solution depends on value of E-V:
- If energy is the same as the potential energy E = V, then:

$$\psi(x) = A + B x$$

- For 1D potential energy functions V(x) (here assume 1D systems)
- Approximation of potential energy V(x) by piece-wise constant V_i
- Schrodinger equation for constant V(x) = V

$$rac{d^2\psi(x)}{dx^2}=-rac{2m}{\hbar^2}(E-V)\psi(x)$$

• Solution depends on value of E-V:

case	solutions	eigenvalue of \hat{p}	parameter
E > V	$e^{\pm ikx}$	$\pm \hbar k$	$k^2=rac{2m}{\hbar^2}(E-V)$
E = V	1, x	0, no e.v.	E = V
E < V	$e^{\mp\kappa x}$	$\pm i \hbar \kappa$	$\kappa^2 = rac{2m}{\hbar^2}(V-E)$

BOUNDARY CONDITIONS ACROSS A STEP IN V(X)

- Suppose there is a step in the potential in x = a.
- Boundary conditions: Continuity of wave function $\psi(x)$ and derivative $\frac{d\psi(x)}{dx}$:

$$\psi_{I}(a) = \psi_{II}(a) \qquad Ae^{ik_{1}a} + Be^{-ik_{1}a} = Ce^{ik_{2}a} + De^{-ik_{2}a}$$

$$\frac{d\psi_{I}(a)}{dx} = \frac{d\psi_{II}(a)}{dx} \qquad ik_{1}Ae^{ik_{1}a} - ik_{1}Be^{-ik_{1}a} = ik_{2}Ce^{ik_{2}a} - ik_{2}De^{-ik_{2}a}$$

$$Ae^{ik_{1}x} + Be^{-ik_{1}x} \qquad Ce^{ik_{2}x} + De^{-ik_{2}x}$$

Lecture 12B: Approximations PART I

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BOUNDARY CONDITIONS ACROSS A STEP IN V(X)

$$\psi_I(a) = \psi_{II}(a) \qquad Ae^{ik_1a} + Be^{-ik_1a} = Ce^{ik_2a} + De^{-ik_2a} \ rac{d\psi_I(a)}{dx} = rac{d\psi_{II}(a)}{dx} \qquad ik_1Ae^{ik_1a} - ik_1Be^{-ik_1a} = ik_2Ce^{ik_2a} - ik_2De^{-ik_2a}$$

$$egin{pmatrix} 1 & 1\ ik_1 & -ik_1 \end{pmatrix} egin{pmatrix} e^{ik_1a} & 0\ 0 & e^{-ik_1a} \end{pmatrix} egin{pmatrix} A\ B \end{pmatrix} = egin{pmatrix} 1 & 1\ ik_2 & -ik_2 \end{pmatrix} egin{pmatrix} e^{ik_2a} & 0\ 0 & e^{-ik_2a} \end{pmatrix} egin{pmatrix} C\ D \end{pmatrix}$$

$$V(x) E$$

$$A e^{ik_1x} + Be^{-ik_1x} Ce^{ik_2x} + De^{-ik_2x}$$

$$E$$
Lecture 12B: Approximations PART I

BOUNDARY CONDITIONS ACROSS A STEP IN V(X)

$$egin{pmatrix} 1 & 1\ ik_1 & -ik_1 \end{pmatrix} egin{pmatrix} e^{ik_1a} & 0\ 0 & e^{-ik_1a} \end{pmatrix} egin{pmatrix} A\ B \end{pmatrix} = egin{pmatrix} 1 & 1\ ik_2 & -ik_2 \end{pmatrix} egin{pmatrix} e^{ik_2a} & 0\ 0 & e^{-ik_2a} \end{pmatrix} egin{pmatrix} C\ D \end{pmatrix}$$

Express coefficient A, B in C, D:

$$egin{split} egin{array}{l} A \ B \end{pmatrix} &= egin{pmatrix} e^{ik_1a} & 0 \ 0 & e^{-ik_1a} \end{pmatrix}^{-1} egin{pmatrix} 1 & 1 \ ik_1 & -ik_1 \end{pmatrix}^{-1} \ & imes egin{pmatrix} X &igin{pmatrix} 1 & 1 \ ik_2 & -ik_2 \end{pmatrix} egin{pmatrix} e^{ik_2a} & 0 \ 0 & e^{-ik_2a} \end{pmatrix} egin{pmatrix} C \ D \end{pmatrix} \end{split}$$

Rename the matrices as function of V and a:

$$egin{pmatrix} A \ B \end{pmatrix} = E_1^{-1}(a)K_1^{-1}K_2E_2(a) \left(egin{array}{c} C \ D \end{array}
ight)$$

TRANSFER MATRIX FOR A SINGLE STEP

$$E_j(a) = egin{pmatrix} e^{ik_j a} & 0 \ 0 & e^{-ik_j a} \end{pmatrix}, \quad K_j egin{pmatrix} 1 & 1 \ ik_j & -ik_j \end{pmatrix}, \ egin{pmatrix} egin{pmatrix} A_1 \ B_1 \end{pmatrix} = E_1^{-1}(a) K_1^{-1} K_2 E_2(a) egin{pmatrix} A_2 \ B_2 \end{pmatrix}$$

We can define the transfer matrix for a single step:

$$T_{12} = E_1^{-1}(a)K_1^{-1}K_2E_2(a)$$

Connection between coefficient before/after step:

$$egin{pmatrix} A_1 \ B_1 \end{pmatrix} = T_{12} \ egin{pmatrix} A_2 \ B_2 \end{pmatrix}$$

MULTIPLE POTENTIAL STEPS

Extending the relation over multiple steps:

$$egin{pmatrix} A_1 \ B_1 \end{pmatrix} = T_{12} \, egin{pmatrix} A_2 \ B_2 \end{pmatrix} = T_{12} \, T_{23} \, egin{pmatrix} A_3 \ B_3 \end{pmatrix}$$

In general, after N steps we obtain:

$$egin{pmatrix} A_0 \ B_0 \end{pmatrix} = T egin{pmatrix} A_{N+1} \ B_{N+1} \end{pmatrix} = T_{01} \, T_{12} \, \ldots \, T_{N,N+1} \, egin{pmatrix} A_{N+1} \ B_{N+1} \end{pmatrix}$$

Or renaming the indices on the left and right:

$$egin{pmatrix} A_L \ B_L \end{pmatrix} = egin{pmatrix} t_{11} & t_{12} \ t_{21} & t_{22} \end{pmatrix} egin{pmatrix} A_R \ B_R \end{pmatrix}$$

SCATTERING AND BOUND STATES

Scattering: $B_R = 0$

$$egin{pmatrix} A_L \ B_L \end{pmatrix} = egin{pmatrix} t_{11} & t_{12} \ t_{21} & t_{22} \end{pmatrix} egin{pmatrix} A_R \ 0 \end{pmatrix}$$

Therefore the transmission and reflection coefficients become:

Transmission
$$T(E) = |A_R/A_L|^2 = 1 / |t_{11}(E)|^2$$

Reflection $R(E) = |B_L/A_L|^2 = |t_{21}(E)|^2 / |t_{11}(E)|^2$



SCATTERING AND BOUND STATES

Bound states: $A_L = 0$, $B_R = 0$

$$\begin{pmatrix} 0\\B_L \end{pmatrix} = \begin{pmatrix} t_{11} & t_{12}\\t_{21} & t_{22} \end{pmatrix} \begin{pmatrix} A_R\\0 \end{pmatrix} \Longrightarrow \begin{array}{c} A_L = t_{11}(E) A_R\\B_L = t_{21}(E) A_R \end{array}$$

- Bound states are given by zeros of t_{11}
- The total wave function is defined upon the coefficients B_L and A_R . We can obtain these unknowns by
 - first using the second equation: $B_L = t_{21}(E) A_R$ to obtain B_L , and then
 - applying normalization to the whole wave function to fix A_R .

